LECTURE 240 – SIMULATION AND MEASUREMENTS OF OP AMPS (READING: AH – 310-323)

Simulation and Measurement Considerations

Objectives:

- The objective of simulation is to verify and optimize the design.
- The objective of measurement is to experimentally confirm the specifications.

Similarity Between Simulation and Measurement:

- Same goals
- Same approach or technique

Differences Between Simulation and Measurement:

- Simulation can idealize a circuit
- Measurement must consider all nonidealities

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Simulating or Measuring the Open-Loop Transfer Function of the Op Amp

Circuit (Darkened op amp identifies the op amp under test):

Simulation:

This circuit will give the voltage transfer function curve. This curve should identify:

- 1.) The linear range of operation
- 2.) The gain in the linear range
- 3.) The output limits
- 4.) The systematic input offset voltage
- 5.) DC operating conditions, power dissipation
- 6.) When biased in the linear range, the small-signal frequency response can be obtained

7.) From the open-loop frequency response, the phase margin can be obtained (F = 1) Measurement:

This circuit probably will not work unless the op amp gain is very low.



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Simulation and Measurement of Open-Loop Frequency Response with Moderate Gain Op Amps



Make *R* as large and measure v_{out} and v_i to get the open loop gain.





Configuration:

Note that $v_I \approx \frac{v_{OS}}{1000}$	$\frac{1}{5}$ or $vOS \approx 1000 v_I$		
How Does this Circuit Work?			
CMRR:	PSRR:		
1.) Set	1.) Set		
V_{DD} ' = V_{DD} + 1V	V_{DD} ' = V_{DD} + 1V		
V_{SS} ' = V_{SS} + 1V	V_{SS} ' = V_{SS}		
v_{OUT} ' = v_{OUT} + 1V	v_{OUT} ' = 0V		
2.) Measure <i>v</i> _{OS}	2.) Measure v_{OS}		
called v_{OS1}	called v_{OS3}		
3.) Set	3.) Set		
V_{DD} ' = V_{DD} - 1V	V_{DD} ' = V_{DD} - 1V		
V_{SS} ' = V_{SS} - 1V	V_{SS} ' = V_{SS}		
v_{OUT} ' = v_{OUT} - 1V	$v_{OUT}' = 0V$		
4.) Measure v_{OS}	4.) Measure v_{OS}		
called v_{OS2}	called v_{OS4}		
5.)	5.)		
2000	2000		
$CMRR = \frac{ v_{OS2} - v_{OS1} }{ v_{OS2} - v_{OS1} }$	$PSRR^+ = \frac{ vOS4 - vOS3 }{ vOS4 - vOS3 }$		
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How Does the Previous Idea Work?

A circuit is shown which is used to measure the *CMRR* and *PSRR* of an op amp. Prove that the *CMRR* can be given as

$$CMRR = \frac{1000 v_{icm}}{v_{os}}$$

<u>Solution</u>

The definition of the common-mode rejection ratio is

$$CMRR = \left|\frac{A_{vd}}{A_{cm}}\right| = \frac{(v_{out}/v_{id})}{(v_{out}/v_{icm})}$$

However, in the above circuit the value of v_{out} is the same so that we get

$$CMRR = \frac{v_{icm}}{v_{id}}$$

But
$$v_{id} = v_i$$
 and $v_{os} \approx 1000v_i = 1000v_{id} \implies v_{id} = \frac{v_{os}}{1000}$

Substituting in the previous expression gives,



~ ~ ~

$$CMRR = \frac{v_{icm}}{\frac{v_{os}}{1000}} = \frac{1000 v_{icm}}{v_{os}}$$

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Simulation of CMRR of an Op Amp

None of the above methods are really suitable for simulation of *CMRR*. Consider the following:



CMRR of Ex. 6.3-1 using the Above Method of Simulation











If the slew rate influences the small signal response, then make the input step size small enough to avoid slew rate (i.e. less than 0.5V for MOS).

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Phase Margin and Peak Overshoot Relationship

It can be shown (Appendix C) that:

Phase Margin (Degrees) = $57.2958cos^{-1}[\sqrt{4\zeta^{4}+1} - 2\zeta^{2}]$

Overshoot (%) = 100
$$exp\left(\frac{-\pi\zeta}{\sqrt{1-\zeta^2}}\right)$$

For example, a 5% overshoot corresponds to a phase margin of approximately 64°.

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Example 1 Simulation of the CMOS Op Amp of Ex. 6.3-1.

The op amp designed in Example 6.3-1 and shown in Fig. 6.3-3 is to be analyzed by SPICE to determine if the specifications are met. The device parameters to be used are those of Tables 3.1-2 and 3.2-1. In addition to verifying the specifications of Example 6.3-1, we will simulate PSRR+ and PSRR-.



Solution/Simulation

The op amp will be treated as a

subcircuit in order to simplify the repeated analyses. The table on the next page gives the SPICE subcircuit description of Fig. 6.3-3. While the values of *AD*, *AS*, *PD*, and *PS* could be calculated if the physical layout was complete, we will make an educated estimate of these values by using the following approximations.

 $AS = AD \cong W[L1 + L2 + L3]$

 $PS = PD \cong 2W + 2[L1 + L2 + L3]$

where L1 is the minimum allowable distance between the polysilicon and a contact in the moat (Rule 5C of Table 2.6-1), L2 is the length of a minimum-size square contact to moat (Rule 5A of Table 2.6-1), and L3 is the minimum allowable distance between a contact to moat and the edge of the moat (Rule 5D of Table 2.6-1).

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Example 1 - Continued

Op Amp Subcircuit:



.SUBCKT OPAMP 1 2 6 8 9 M1 4 2 3 3 NMOS1 W=3U L=1U AD=18P AS=18P PD=18U PS=18U M2 5 1 3 3 NMOS1 W=3U L=1U AD=18P AS=18P PD=18U PS=18U M3 4 4 8 8 PMOS1 W=15U L=1U AD=90P AS=90P PD=42U PS=42U M4 5 4 8 8 PMOS1 W=15U L=1U AD=90P AS=90P PD=42U PS=42U M5 3 7 9 9 NMOS1 W=4.5U L=1U AD=27P AS=27P PD=21U PS=21U M6 6 5 8 8 PMOS1 W=94U L=1U AD=564P AS=564P PD=200U PS=200U M7 6 7 9 9 NMOS1 W=14U L=1U AD=84P AS=84P PD=40U PS=40U M8 7 7 9 9 NMOS1 W=4.5U L=1U AD=27P AS=27P PD=21U PS=21U CC 5 6 3.0P .MODEL NMOS1 NMOS VTO=0.70 KP=110U GAMMA=0.4 LAMBDA=0.04 PHI=0.7 +MJ=0.5 MJSW=0.38 CGBO=700P CGSO=220P CGDO=220P CJ=770U CJSW=380P +LD=0.016U TOX=14N .MODEL PMOS1 PMOS VTO=-0.7 KP=50U GAMMA=0..57 LAMBDA=0.05 PHI=0.8 +MJ=0.5 MJSW=.35 CGBO=700P CGSO=220P CGDO=220P CJ=560U CJSW=350P +LD=0.014U TOX=14N **IBIAS 8 7 30U** .ENDS

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Example 1 - Continued PSPICE Input File for the Open-Loop Configuration:

EXAMPLE 1 OPEN LOOP CONFIGURATION .OPTION LIMPTS=1000 VIN+ 1 0 DC 0 AC 1.0 VDD 4 0 DC 2.5 VSS 0 5 DC 2.5 VIN - 2 0 DC 0 CL 3 0 10P X1 1 2 3 4 5 OPAMP (Subcircuit of previous slide) .OP .TF V(3) VIN+ .DC VIN+ -0.005 0.005 100U .PRINT DC V(3) .AC DEC 10 1 10MEG .PRINT AC VDB(3) VP(3) .PROBE (This entry is unique to PSPICE) .END

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Example 1 - Continued

Open-loop transfer characteristic of Example 6.3-1:



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Why the negative overshoot on the slew rate?

If M7 cannot sink sufficient current then the output stage slews and only responds to changes at the output via the feedback path which involves a delay.

Note that $-dv_{out}/dt \approx -2V/0.3\mu s = -6.67V/\mu s$. For a 10pF capacitor this requires 66.7µA and only 95µA-66.7µA = 28µA is available for C_c . For the positive slew rate, M6 can provide whatever current is required by the capacitors and can immediately respond to changes at the output. ECE 6412 - Analog Integrated Circuit Design - II



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Example 1 - Continued

Why is the negative-going overshoot larger than the positive-going overshoot on the small-signal transient response of the last slide?

Consider the following circuit and waveform:



During the rise time,

(The material beneath this box is part of a homework solution)

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Example 1 - Continued

Comparison of the Simulation Results with the Specifications of Example 6.3-1:

Specification	Design	Simulation
(Power supply = ± 2.5 V)	(Ex. 6.3-1)	(Ex. 1)
Open Loop Gain	>5000	10,000
GB (MHz)	5 MHz	5 MHz
Input CMR (Volts)	-1V to 2V	-1.2 V to 2.4 V,
Slew Rate (V/µsec)	>10 (V/µsec)	+10, -7(V/µsec)
Pdiss (mW)	< 2mW	0.625mW
V _{out} range (V)	±2V	+2.3V, -2.2V
PSRR+(0) (dB)	-	87
PSRR- (0) (dB)	-	106
Phase margin (degrees)	60°	65°
Output Resistance ($k\Omega$)	-	122.5kΩ

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SUMMARY

Simulation is a key step in electrical design - it is the step to verify and optimize Measurement is a key step in the overall design - electrical \rightarrow physical \rightarrow measurement Similarities between simulation and measurement:

- Same desired responses
- Same general method to approach the result

Dissimilarities between simulation and measurement:

- Measurement using nonideal components and simulation has ideal components
- Can access internal nodes with simulation
- Can create artificial configurations with simulation
- Parasitics are a problem with measurement