

## **LECTURE 360 – CHARACTERIZATION OF COMPARATORS**

### **(READING: AH – 439-444)**

#### **Objective**

The objective of this presentation is:

- 1.) Introduction to the comparator
- 2.) Characterization of the comparator

#### **Outline**

- Static characterization
- Dynamic characterization
- Summary

#### **What is a Comparator?**

The comparator is essentially a 1-bit analog-digital converter.

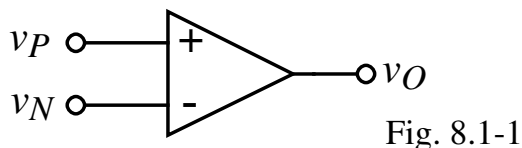
Input is analog

Output is digital

Types of comparators:

- 1.) Open-loop (op amps without compensation)
- 2.) Regenerative (use of positive feedback - latches)
- 3.) Combination of open-loop and regenerative comparators

## Circuit Symbol for a Comparator



### Static Characteristics

- Gain
- Output high and low states
- Input resolution
- Offset
- Noise

### Dynamic Characteristics

- Propagation delay
- Slew rate

## Noninverting and Inverting Comparators

The comparator output is binary with the two-level outputs defined as,

$V_{OH}$  = the high output of the comparator

$V_{OL}$  = the low level output of the comparator

Voltage transfer function of an Noninverting and Inverting Comparator:

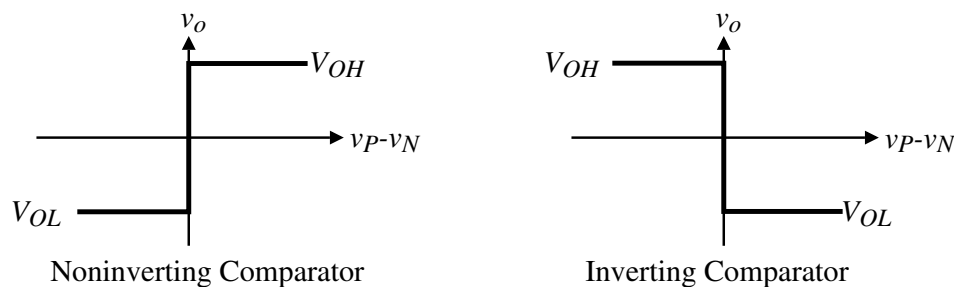


Fig. 8.1-2A

## Static Characteristics - Zero-order Model for a Comparator

Voltage transfer function curve:

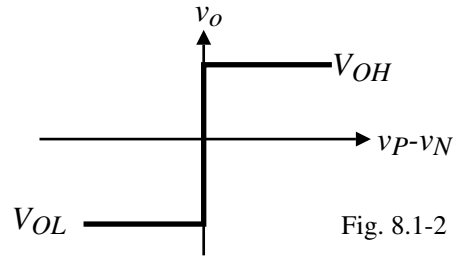
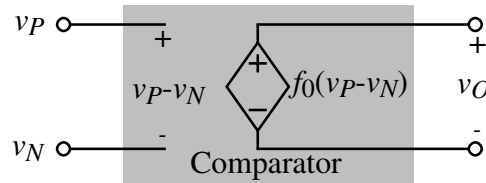


Fig. 8.1-2

Model:



$$f_0(v_P - v_N) = \begin{cases} V_{OH} & \text{for } (v_P - v_N) > 0 \\ V_{OL} & \text{for } (v_P - v_N) < 0 \end{cases} \quad \text{Fig. 8.1-3}$$

$$\text{Gain} = A_v = \lim_{\Delta V \rightarrow 0} \frac{V_{OH} - V_{OL}}{\Delta V} \quad \text{where } \Delta V \text{ is the input voltage change}$$

## Static Characteristics - First-Order Model for a Comparator

Voltage transfer function curve:

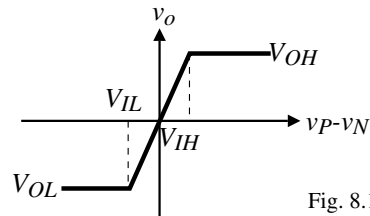


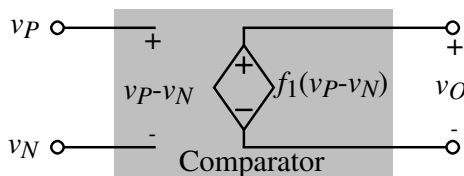
Fig. 8.1-4

where for a noninverting comparator,

$V_{IH}$  = smallest input voltage at which the output voltage is  $V_{OH}$

$V_{IL}$  = largest input voltage at which the output voltage is  $V_{OL}$

Model:



$$f_1(v_P - v_N) = \begin{cases} V_{OH} & \text{for } (v_P - v_N) > V_{IH} \\ A_v(v_P - v_N) & \text{for } V_{IL} < (v_P - v_N) < V_{IH} \\ V_{OL} & \text{for } (v_P - v_N) < V_{IL} \end{cases} \quad \text{Fig. 8.1-5}$$

$$\text{The voltage gain is } A_v = \frac{V_{OH} - V_{OL}}{V_{IH} - V_{IL}}$$

## Static Characteristics - First-Order Model including Input Offset Voltage

Voltage transfer curve:

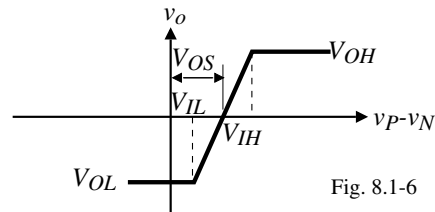


Fig. 8.1-6

$V_{OS}$  = the input voltage necessary to make the output equal  $\frac{V_{OH}+V_{OL}}{2}$  when  $v_P = v_N$ .

Model:

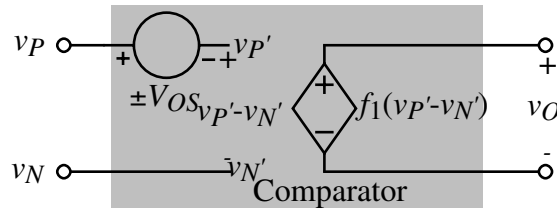


Fig. 8.1-7

Other aspects of the model:

$ICMR$  = input common mode voltage range (all transistors remain in saturation)

$R_{in}$  = input differential resistance

$R_{icm}$  = common mode input resistance

## Static Characteristics - Comparator Noise

Noise of a comparator is modeled as if the comparator were biased in the transition region.

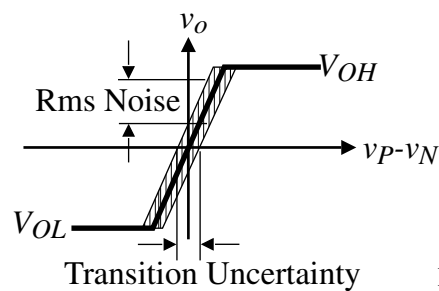


Fig. 8.1-8

Noise leads to an uncertainty in the transition region which causes jitter or phase noise.

## Dynamic Characteristics - Propagation Time Delay

Rising propagation delay time:

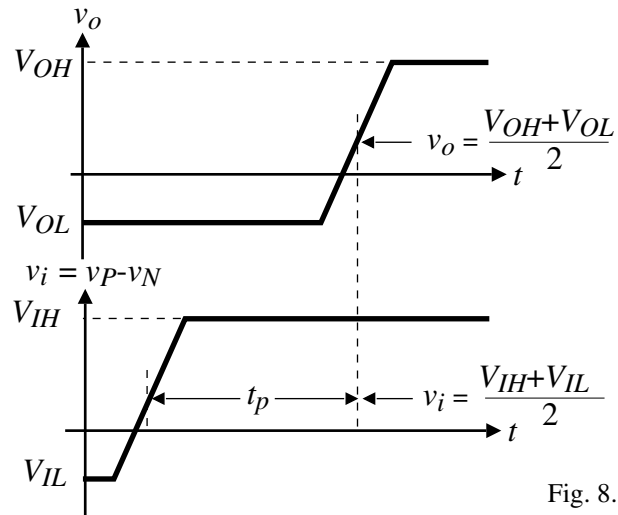


Fig. 8.1-9

$$\text{Propagation delay time} = \frac{\text{Rising propagation delay time} + \text{Falling propagation delay time}}{2}$$

## Dynamic Characteristics - Single-Pole Response

Model:

$$A_v(s) = \frac{A_v(0)}{s} = \frac{A_v(0)}{s\tau_c + 1}$$

where

$A_v(0)$  = dc voltage gain of the comparator

$\omega_c = \frac{1}{\tau_c}$  = -3dB frequency of the comparator or the magnitude of the pole

Step Response:

$$v_o(t) = A_v(0) [1 - e^{-t/\tau_c}] V_{in}$$

where

$V_{in}$  = the magnitude of the step input.

### Dynamic Characteristics - Propagation Time Delay

The rising propagation time delay for a single-pole comparator is:

$$\frac{V_{OH}-V_{OL}}{2} = A_v(0) [1 - e^{-t_p/\tau_c}] V_{in} \rightarrow t_p = \tau_c \ln \left[ \frac{1}{1 - \frac{V_{OH}-V_{OL}}{2A_v(0)V_{in}}} \right]$$

Define the minimum input voltage to the comparator as,

$$V_{in(min)} = \frac{V_{OH}-V_{OL}}{A_v(0)} \rightarrow t_p = \tau_c \ln \left[ \frac{1}{1 - \frac{V_{in(min)}}{2V_{in}}} \right]$$

Define  $k$  as the ratio of the input step voltage,  $V_{in}$ , to the minimum input voltage,  $V_{in(min)}$ ,

$$k = \frac{V_{in}}{V_{in(min)}} \rightarrow t_p = \tau_c \ln \left[ \frac{2k}{2k-1} \right]$$

Thus, if  $k = 1$ ,  $t_p = 0.693\tau_c$ .

Illustration:

Obviously, the more overdrive applied to the input, the smaller the propagation delay time.

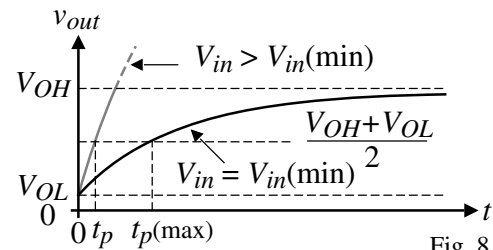
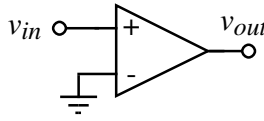


Fig. 8.1-10

### Dynamic Characteristics - Slew Rate of a Comparator

If the rate of rise or fall of a comparator becomes large, the dynamics may be limited by the slew rate.

Slew rate comes from the relationship,

$$i = C \frac{dv}{dt}$$

where  $i$  is the current through a capacitor and  $v$  is the voltage across it.

If the current becomes limited, then the voltage rate becomes limited.

Therefore for a comparator that is slew rate limited we have,

$$t_p = \Delta T = \frac{\Delta V}{SR} = \frac{V_{OH}-V_{OL}}{2 \cdot SR}$$

where

$SR$  = slew rate of the comparator.

### **Example 1 - Propagation Delay Time of a Comparator**

Find the propagation delay time of an open loop comparator that has a dominant pole at  $10^3$  radians/sec, a dc gain of  $10^4$ , a slew rate of  $1\text{V}/\mu\text{s}$ , and a binary output voltage swing of  $1\text{V}$ . Assume the applied input voltage is  $10\text{mV}$ .

#### **Solution**

The input resolution for this comparator is  $1\text{V}/10^4$  or  $0.1\text{mV}$ . Therefore, the  $10\text{mV}$  input is 100 times larger than  $v_{in}(\text{min})$  giving a  $k$  of 100. Therefore, we get

$$t_p = \frac{1}{10^3} \ln\left(\frac{2 \cdot 100}{2 \cdot 100 - 1}\right) = 10^{-3} \ln\left(\frac{200}{199}\right) = 5.01\mu\text{s}$$

For slew rate considerations, we get

$$t_p = \frac{1}{2 \cdot 1 \times 10^6} = 0.5\mu\text{s}$$

Therefore, the propagation delay time for this case is the larger or  $5.01\mu\text{s}$ .

### **SUMMARY**

- A comparator is a one-bit ADC
- Comparators can be noninverting or inverting
- Types of comparators include:
  - Open-loop
  - Regenerative
  - Open-loop and regenerative
- Static Characteristics
  - Gain
  - Output high and low states
  - Input resolution
  - Offset
  - Noise
- Dynamic Characteristics
  - Propagation delay
  - Slew rate