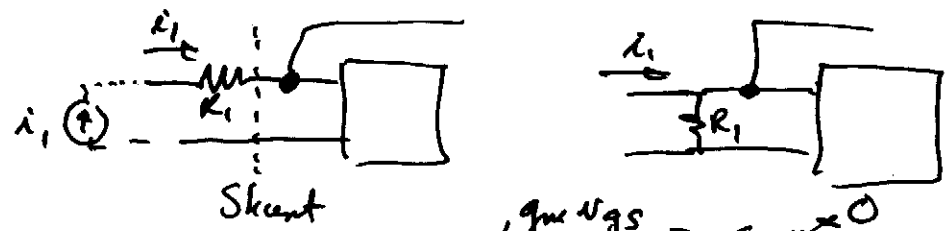


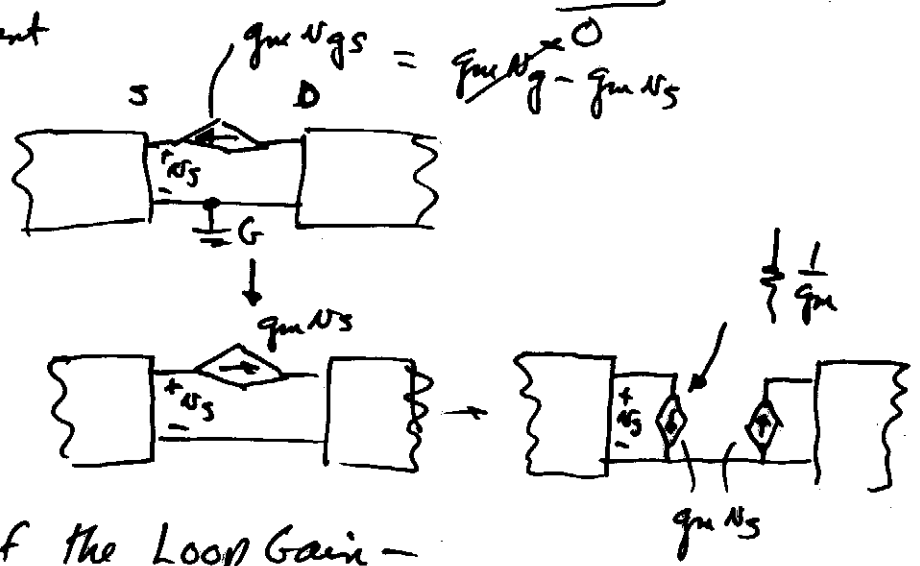
Comments on Quiz #12

1.) The units of A change with the 4 fb. topologies.

2.) Current driven



3.)

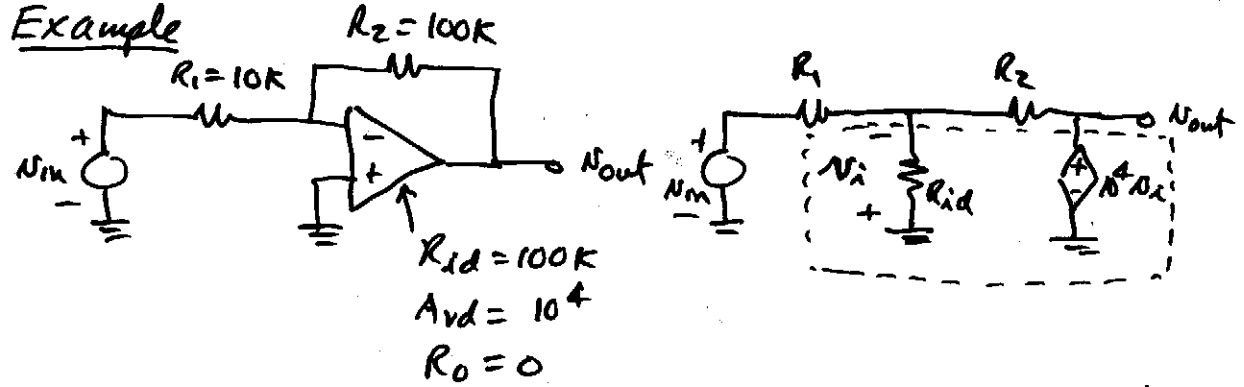


Calculation of the Loop Gain -

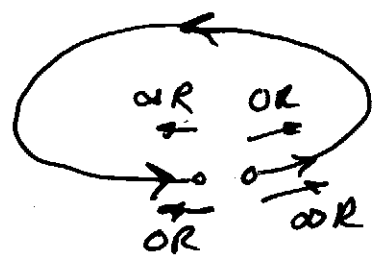
1.) Direct

2.) Successive voltage and current xxx

Example

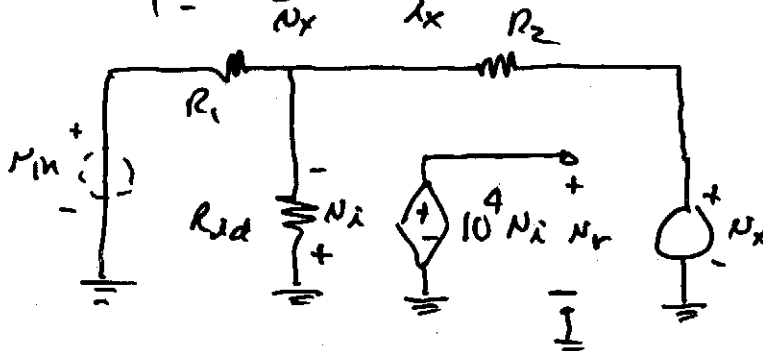


When you apply the direct method look for points of ∞ resistance or 0 resistance.





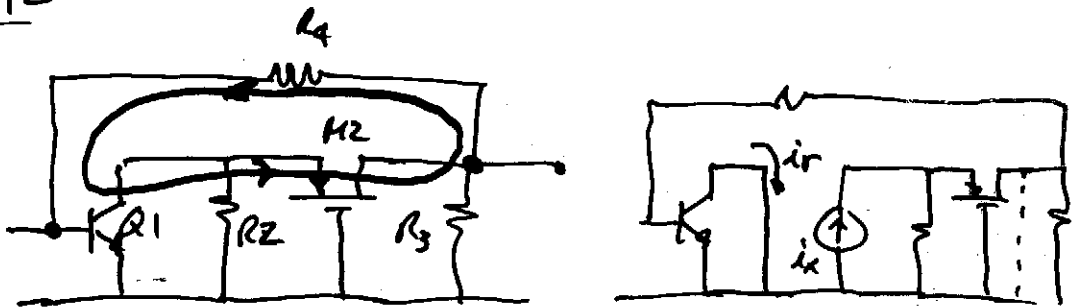
$$T = -\frac{N_r}{N_x} = \frac{-i_r}{i_x}$$



$$N_x = 10^4 N_i = 10^4 \left(\frac{-R_1 R_{id}}{R_1 R_{id} + R_2} \right) \frac{N_r}{10^4}$$

$$\therefore T = -\frac{N_r}{N_x} = \left(\frac{10^4 (R_1 R_{id})}{R_1 R_{id} + R_2} \right) = \frac{10^4 \cdot 9.09k}{(9.09 + 100)k} = \underline{\underline{E3.33}}$$

Quiz 12



Stability of feedback Amplifiers

$$A_F = \frac{A}{1+AB} \rightarrow A_F(s) = \frac{A(s)}{1+A(s)B(s)} = \frac{A(s)}{1+T(s)} \quad \left(\frac{A(s)}{1+T(s)} \right)$$

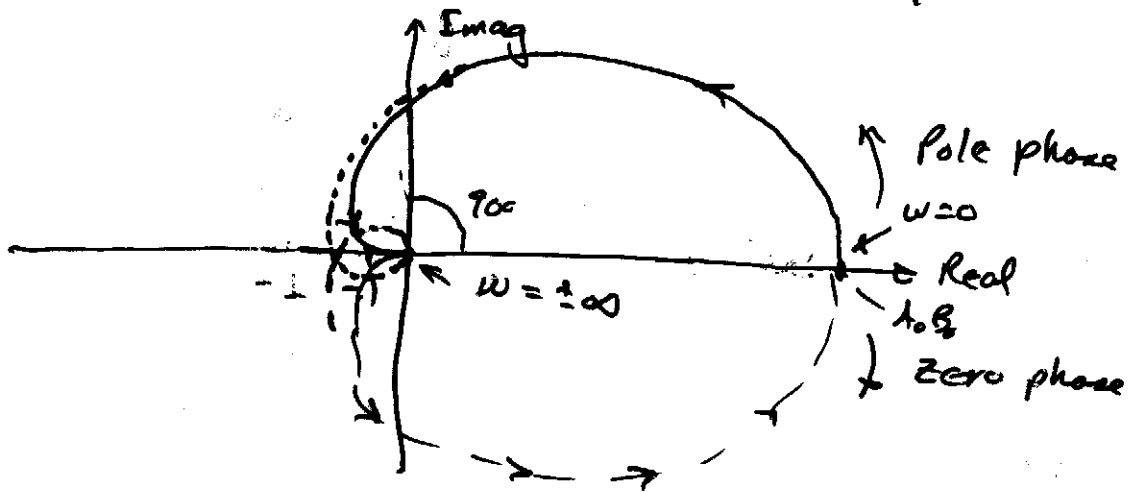
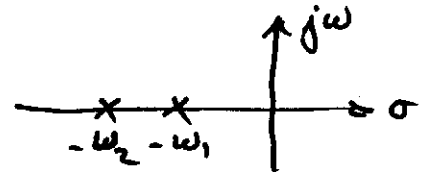
Roots of denominators (poles) must be in the LHP.

Two approaches to determining stability

1.) Nyquist plot

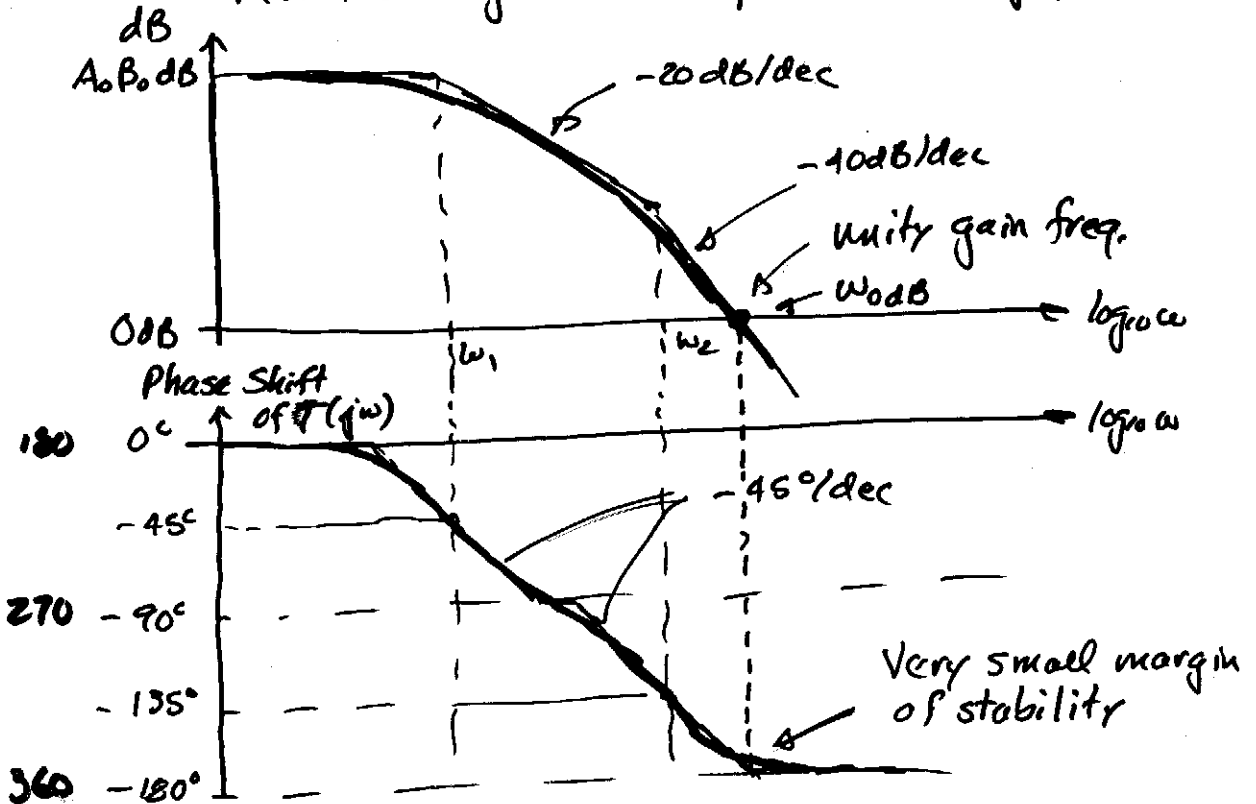
Plot $T(j\omega)$ on a complex plane for values of ω varying from 0 to $+\infty$, $-\infty$ to 0. If this plot encloses the -1, the amplifier is unstable.

$$T(s) = A(s)B = \frac{A_0 B_0}{(\frac{s}{\omega_1} + 1)(\frac{s}{\omega_2} + 1)}$$



2.) Bode Plots

Plot the magnitude and phase of $T(j\omega)$



A feedback amplifier is stable iff-

a.) $\text{Arg}[T(j\omega_{-180})] > -180^\circ$ ω_{-180} is when Phase = -180°

b.) $|T(j\omega_{-180})| < 1$

